### Introduction to the Theorema system

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- 2 Algorithm synthesis
- 3 Algorithm verification



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### The Theorema system

#### Web page:

www.risc.jku.at/theorema

• Conceived and initiated around 1995 by *Bruno Buchberger* and reflects his view of "doing mathematics".

#### Theorema 2.0 is a major re-launch

• Mainly developed by Wolfgang Windsteiger.

Implementation: Mathematica

• Proving uses only the rewrite mechanism of Mathematica.

#### Supports:

- Development of mathematical theories in natural style.
- Proving in natural style.
- Definition and execution of algorithms.
- Construction of provers for various domains.

#### Installation

#### Home page:

www.risc.jku.at/research/theorema/software

#### User mode

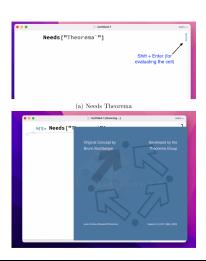
- Mathematica software needed
- Download the Theorema package and copy it in the Mathematica folder

#### Developer mode

- Needed: Mathematica, Eclipse, JDK, Workbench
- Download the Theorema package and include it in Eclipse
- Installation guide here.

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# Loading Theorema in user mode



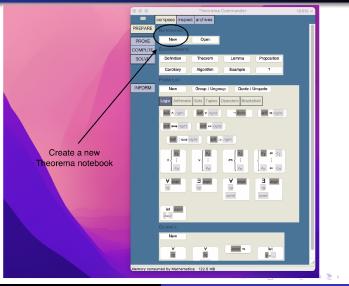
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Introduction to the Theorema System

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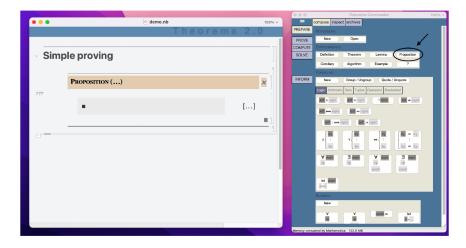


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# Proving



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Algorithm synthesis Algorithm verification Conclusions

# Proving

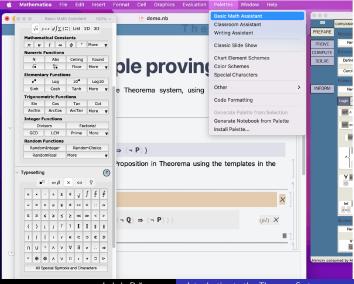
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Algorithm synthesis Algorithm verification Conclusions

# Proving



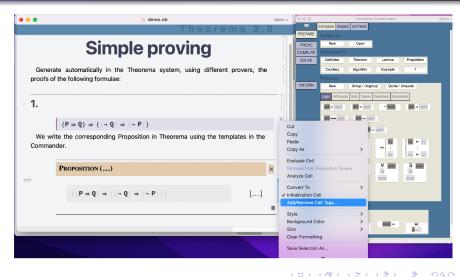
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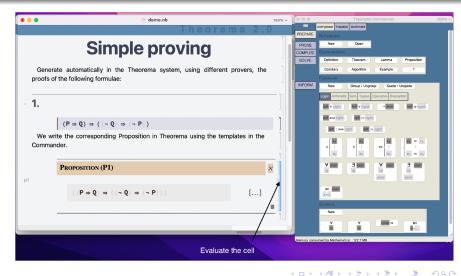
# Proving



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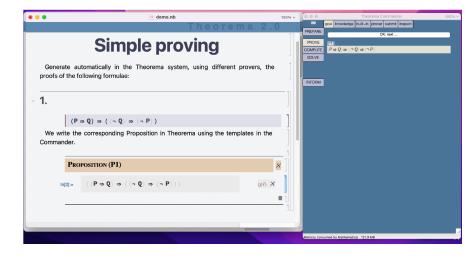
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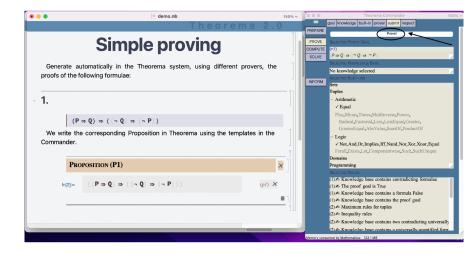
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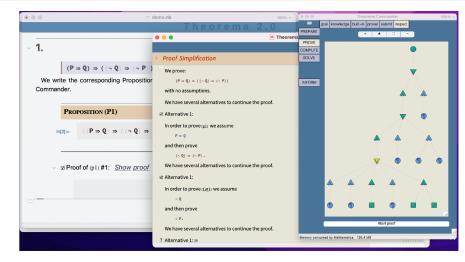


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### The proof and the proof tree



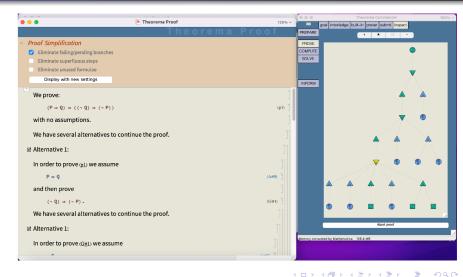
#### Isabela Drămnesc Introduction to the Theorema System

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# Simplify the proof



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## Both simplified and full proof

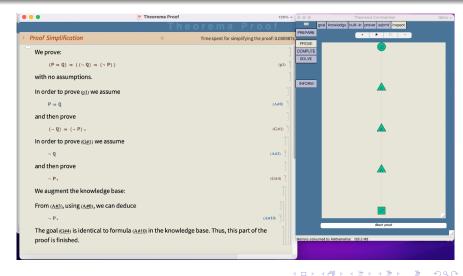
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#### The simplified proof



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## Exercises (proving)

Exercises. Consider the following formulae:

- $1. \ (P \Longrightarrow Q) \Longrightarrow (Q \Longrightarrow P)$
- $2. \ P \lor (P \Longrightarrow Q)$
- $3. \ ((P \Longrightarrow Q) \land (Q \Longrightarrow R)) \Longrightarrow ((P \land Q) \Longrightarrow R)$
- $4. \ ((Q \Longrightarrow P) \land (Q \Longrightarrow R)) \Longrightarrow ((P \lor Q) \Longrightarrow R)$

For each of these formulae:

- (a) following the examples shown, generate both the full proof and the simplified proofs in the Theorema system;
- (b) generate in Theorema different proofs by choosing different provers, different inference rules to be applied, change the search depth, change the search time;

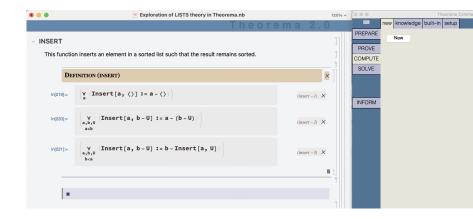
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#### Theory exploration

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#### Compute with definitions

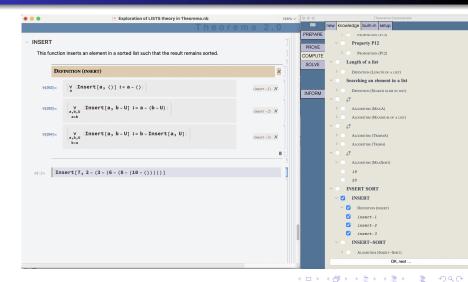


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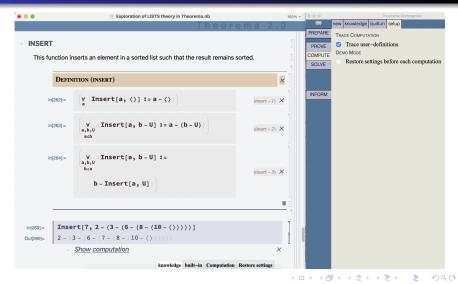
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#### **Compute Insert**



## Show computation steps

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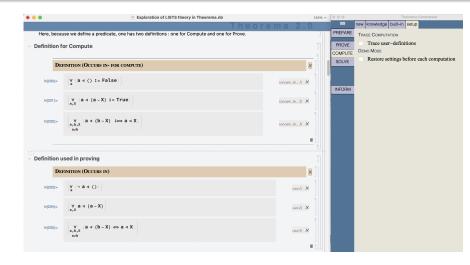
#### Compute with predicate definitions

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#### Compute with predicate definitions



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## References

[1] Isabela Drămnesc, Erika Ábrahám, Tudor Jebelean, Gábor Kusper, and Sorin Stratulat. **Experiments with Automated Reasoning in the Class**. In Proc. of the 15th International Conference on Intelligent Computer Mathematics (CICM'22), volume 13467 of LNCS, pages 287–304. Springer, 2022, Tbilisi, Georgia.

[2] Isabela Drămnesc, Erika Ábrahám, Tudor Jebelean, Gábor Kusper, Sorin Stratulat, **ARC: An Educational Project on Automated Reasoning in the Class** In Proceedings of EdMedia+ Innovate Learning 2022, pages 934–943, 2022, New York City, USA, AACE.

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Acknowledgements: This work was co-funded by the European Union, Erasmus+ project **ARC: Automated Reasoning in the Class**, 2019-1-RO01-KA203-063943, 2019 - 2022,

www.arc.info.uvt.ro

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# AlCons: A Prover for Deductive Synthesis of Sorting Algorithms in *Theorema*

Outline

- Problem and approach
- AlCons implementation overview
- Demo in Theorema
  - Algorithm generation on binary trees
  - Compute with the extracted algorithm

# Algorithm synthesis

Starting from a specification of a problem

• find an algorithm which satisfies the specification including auxiliary algorithms (subroutines)

#### Synthesis by proving:

- $\bullet \ \ {\rm specification} \ \longrightarrow \ {\rm conjecture}$
- prove
- proof  $\longrightarrow$  algorithm

#### Main goal:

 Design methods, inference rules and strategies for constructing proofs (efficient, natural style) and for synthesizing auxiliary functions.

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## Motivation

**Study** the structure of natural style proving.

**Explore** the appropriate theories (by adding properties and functions to the knowledge base during proof attempts).

**Find** efficient proof strategies and inference rules appropriate to the domains of lists, binary trees, and multisets.

**Use** multisets to express naturally the fact that two lists/trees have the same elements and to guide the synthesis proof.

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## Problem and Method

**Problem:** Given a specification, find a correct algorithm. **Specification:** Input condition (*I*), output condition (*O*). **Synthesis conjectures:** 

- Unary functions:  $\forall_X (I[X] \implies \exists O[X, Y]).$
- Binary functions:  $\forall \forall (I[X, Y] \implies \exists O[X, Y, Z]).$

Proofs:

- Automatically generated by AlCons:
  - $\bullet \ \text{success: proof} \longrightarrow \text{algorithm}$
  - failure: "cascading" (generates further synthesis conjectures for synthesis of auxiliary functions)

#### Algorithm extraction:

• One or more algorithms from one proof.

Case studies: Sorting of lists and binary trees.

### Types

Elements: a, b, ctotal order:  $a < b, a \le b$ 

Lists: U, V, W, X, Yinductive domain:  $\langle \rangle$ ,  $a \sim U$ extended order: a < U,  $a \le U$ , U < a,  $U \le a$ , U < V,  $U \le V$ 

**Binary trees**: *L*, *R*, *S*, *T*, *X*, *Y*, *Z* inductive domain:  $\varepsilon$ ,  $\langle L, a, R \rangle$ extended order: a < L,  $a \le L$ , L < a,  $L \le a$ , L < R,  $L \le R$ 

#### Multisets:

$$\begin{array}{c|c} \mathcal{M}[\langle\rangle] = \emptyset & \mathcal{M}[\varepsilon] = \emptyset \\ \mathcal{M}[\mathsf{a} \smile \mathsf{V}] = \{\{\mathsf{a}\}\} \uplus \mathcal{M}[\mathsf{V}] & \mathcal{M}[\langle \mathsf{L}, \mathsf{a}, \mathsf{R} \rangle] = \mathcal{M}[\mathsf{L}] \uplus \{\{\mathsf{a}\}\} \uplus \mathcal{M}[\mathsf{R}] \end{array}$$

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# AlCons: Implementation Overview

**The prover: a collection of rewrite rules** corresponding to inferences (called *proof steps*).

- $\bullet$  a proof situation (assm, goal)  $\stackrel{\mathrm{rule}}{\longrightarrow}$  new proof situation
- Alternatives: an AND-OR proof tree is created,
- In contrast to the usual behavior of *Theorema* provers,
   AICons follows *all alternatives* —> may lead to different algorithms.
- Some of the alternatives may also fail the *termination* is ensured by the *Theorema* mechanism for controlling the depth of the proof tree.

#### Implementation Overview

AlCons is a *first order* prover based on the methods:

- *Classical* propositional and first order inferences similar to the ones from sequent calculus.
- Cover set induction applied both to universal and to existential goals.
- *Domain specific* methods for the types handled by the prover (multisets, lists, and binary trees).

These methods are implemented as:

- *Inference rules*: describe how to change the proof status in one proof step.
- Strategies: describe how to combine several inference rules.

# Cover Set: Set of terms covering the domain.

Each element of the domain instantiates exactly one cover term. For binary trees:  $\{\varepsilon, \langle L, a, R \rangle\}$  (L, a, R: variables). Target goal:  $\forall \exists P[X, Y] \xrightarrow{\text{Skolem}} \exists P[X_0, Y] \xrightarrow{\text{metavar}} P[X_0, Y^*]$   $X_0$ : target constant,  $Y^*$ : target metavariable **On Skolem constants**: Prove  $P[\varepsilon, Y^*]$  and  $P[\langle L_0, a_0, R_0 \rangle, Y^*]$ 

- may use  $P[L_0, F[L_0]]$  and  $P[L_0, F[R_0]]$  (F: synth. funct.)
- determines the decomposition of the input

#### On metavariables:

Prove  $P[X_0, \varepsilon]$  and  $P[X_0, \langle L^*, a^*, R^* \rangle]$ 

- may replace  $L^*$  by  $F[L_1^*]$  and  $R^*$  by  $F[R_1^*]$
- determines the structure of the output

In a nested way on the new Skolem constants and metavariables

 $\longrightarrow$  Algorithms with nested recursion, and with recursion on

several arguments

#### Dynamic induction

Dynamically generates new induction hypotheses during the proof.

**Noetherian induction** based on the well-founded ordering:  $L \prec R$  is  $\mathcal{M}[L] \subset \mathcal{M}[R]$ 

Checked *syntactically* at meta-level: meta-relation between terms induced by the strict inclusion of the multisets of symbols

• Example:  $\langle L_0, a_0, R^* \rangle \prec \langle L_0, a_0, \langle R^*, b_0, S^* \rangle \rangle$ 

Usage:

- ground term t ≺ X<sub>0</sub> (target constant): add P[t, Sort[t]] to assumptions.
- metavariable L<sup>\*</sup> ≺ Y<sup>\*</sup> (target metavariable): replace in goal L<sup>\*</sup> by F[L<sup>\*</sup>] (target function applied to a new metavariable)

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# Strategy: Cascading (conjecture generation)

Synthesizing auxiliary functions:

- generate conjecture
- prove conjecture  $\longrightarrow$  algorithm
- use auxiliary function in proof

Conjecture generation:

- Skolem constants from goal  $\longrightarrow$  universal  $x, x', \dots$
- metavariables from goal  $\longrightarrow$  existential  $y, y', \ldots$
- conjecture:

$$\forall \forall \dots (P[x, x', \dots] \Longrightarrow \exists \exists \dots Q[x, x', \dots, y, y', \dots])$$

- *P*[*x*, *x'*,...]: from the assumptions containing <u>only</u> the Skolem constants present in goal
- $Q[x, x', \dots, y, y', \dots]$ : from the goal

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# Strategy: Cascading (function usage)

Using the generated functions F[x, x', ...], F'[x, x', ...]:

• new assumption:

$$\forall \forall \dots (P[x, x', \dots] \Longrightarrow Q[x, x', \dots, F[x, x', \dots], F'[x, x', \dots], \dots])$$

- use the new function symbols in the goal
- contributes to automatic theory exploration

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# Group multisets

The goal contains the equality:  $\mathcal{M}[Y^*] = \mathcal{M}[t_1] \uplus \mathcal{M}[t_2] \uplus \dots$ Proof flow: transform the union into  $\mathcal{M}[t]$  (then  $Y^* = t$ ) Stepwise: groups pairs  $\mathcal{M}[t_1] \uplus \mathcal{M}[t_2]$ (different groupings  $\longrightarrow$  proof alternatives)

For each pair, find the function F such that:

$$\mathcal{M}[\mathit{F}[t_1, t_2]] = \mathcal{M}[t_1] \uplus \mathcal{M}[t_2]$$

Possibilities:

- F is already known, the proof works by predicate logic;
- induction can be applied (if F is the target function)
- cascading is necessary for the synthesis of F

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# Example: Group multisets and cascading

The goal is:  $IsSorted[Y^*] \land \mathcal{M}[Y^*] = \mathcal{M}[a_0] \uplus \mathcal{M}[R_0] \uplus \dots$ The assumptions contain:  $IsSorted[R_0]$ 

Group pair:  $\mathcal{M}[a_0] \uplus \mathcal{M}[R_0]$ 

Cascading: synthesize *Insert* from the conjecture:

 $\forall \forall \exists (\mathit{IsSorted}[R] \implies (\mathit{IsSorted}[Y] \land \mathcal{M}[Y] = \mathcal{M}[a] \uplus \mathcal{M}[R]))$ 

Add new assumption:

 $IsSorted[R] \implies (IsSorted[Insert[a, R]] \land \mathcal{M}[Insert[a, R]] = \mathcal{M}[a] \uplus \mathcal{M}[R])$ 

Change goal to:  $IsSorted[Y^*] \land \mathcal{M}[Y^*] = Insert[a_0, R_0] \uplus \dots$ 

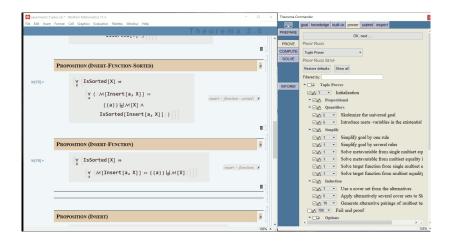
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The extracted algorithm: set of conditional equalities

- $\{Q_k \Rightarrow (F[\mathcal{X}] = T_k)\}_{k=1}^n (\mathcal{X} \text{ is a pattern cover set term})$
- $Q_k$  are formulae;  $T_k$  are terms (dependent on variables of the pattern)

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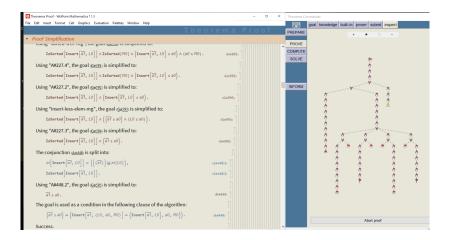
## Proving in Theorema



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## Generated Proof and Proof Tree in Theorema



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## AlCons Demo

- The automatically generated proof of the above conjecture, by AICons.
- Basic properties used in the proof.
- Highligthing the solutions obtained.
- The extracted algorithm from the proof.

#### **Proof animation**

# Computation with the Extracted Algorithm

	Theorem	a 2.t			Prepare	OK, ni	ot
The ex	tracted algorithm is:			1^	Prove	Filtered by:	Show all
	Algorithm (Insert an element in a tree)		×		Compute	Experiments-AlgorithmConstructor	
	$\left( \begin{array}{c} \forall \ (\texttt{Insert}[\texttt{a}, \ \epsilon] := \langle \epsilon, \ a, \ \epsilon \rangle ) \end{array} \right)$	( <i>D10</i> )	×		Solve	Algorithm (Insert an element in a     D10	2798)
	$ \left( \begin{array}{c} \forall \\ a, b, L, R \\ ab \end{array} \right) (Insert[a, \langle L, b, R \rangle] := \langle Insert[a, L], b, R \rangle) \\ ab \end{array} $	(DII)	×		Inform	D11 D23	
	$\left( \begin{array}{c} v \\ a, b, L, R \\ a > b \end{array} \\ \left( \begin{array}{c} Insert[a, \langle L, b, R \rangle] := \langle L, b, Insert[a, R] \rangle \right) \\ a > b \end{array} \right)$	(Dl3)	×			OK, n	ot
in(5):= u1(5)=	<pre>Insert[3, c]</pre>						
in(6):= ut(6)=	<pre>Insert[3, ⟨ε, 5, ε⟩] (⟨ε, 3, ε⟩, 5, ε⟩</pre>						
h(7):= ut(7)=	Insert[3, $\langle \langle \epsilon, 3, \epsilon \rangle, 5, \epsilon \rangle$ ] $\langle \langle \langle \epsilon, 3, \epsilon \rangle, 3, \epsilon \rangle, 5, \epsilon \rangle$						
in(8):- 1u((8)-	$\begin{array}{l} \texttt{Insert[10, (\langle \epsilon, 3, \epsilon \rangle, 5, \langle \epsilon, 7, \langle \epsilon, 10, \epsilon \rangle \rangle )]} \\ \langle \langle \epsilon, 3, \epsilon \rangle, 5, \langle \epsilon, 7, \langle \langle \epsilon, 10, \epsilon \rangle, 10, \epsilon \rangle \rangle \rangle \end{array}$						
n(9):= ut(9)=	$ \begin{array}{l} \textbf{Insert[2, \langle \langle \epsilon, 3, \epsilon \rangle, 5, \langle \epsilon, 7, \langle \epsilon, 10, \epsilon \rangle \rangle \rangle } \\ \langle \langle \langle \epsilon, 2, \epsilon \rangle, 3, \epsilon \rangle, 5, \langle \epsilon, 7, \langle \epsilon, 10, \epsilon \rangle \rangle \rangle \end{array} $						
	Insert[22, $\langle \langle \varepsilon, 3, \varepsilon \rangle, 5, \langle \varepsilon, 7, \langle \varepsilon, 10, \varepsilon \rangle \rangle \rangle$ ]						

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#### Results

- **AICons**: a powerful system for proof-based algorithm synthesis on lists and binary trees using multisets.
- The proofs are generated in a few seconds and are easy to understand.
- The most important proof strategies are: use cover sets together with multiset based Noetherian induction, pairing of multisets, and cascading.
- By using cover sets, no algorithm scheme and no concrete induction principles are needed in advance, as they are dynamically produced during the proof, and even nested induction algorithms can be generated automatically.

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# Verification of algorithms in Theorema

#### Outline

- Problem and approach
- Implementation overview: some special rules
- Results

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# Problem and Method

**Problem:** Given an algorithm, prove that the algorithm is correct (including the verification of auxiliary algorithms).

Specification: the output is sorted and preserves the multiset.

 $\longrightarrow$  two logical conjectures

Proofs:

- Automatically generated by the *Theorema* prover:
  - $\bullet\,$  success: proof  $\longrightarrow$  the correctness of the algorithm
  - failure: "cascading" (generates further conjectures for verification of auxiliary functions)
- Script in Coq

#### Case study

 Verification of: Bubble–Sort, Insert–Sort, Merge–Sort, Quick–Sort, Patience–Sort, Min–Sort, Max–Sort, Min–Max–Sort on lists, by using the Theorema and Coq systems.

# Motivation

Algorithm certification or program verification have an *increasing importance* in the current technological landscape, due to the sharp increase in the complexity of software (adverse effects in case of failure)

• for instance robots constitute a particular class of systems that can present high risks of software failures.

Sorting has a growing area of applications,

• in particular the ones where organizing huge data collections is critical, as for instance in environmental applications.

**Compare** the characteristics and the performance of **Theorema and Coq**.

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#### The logical conjecture in Theorema

# $\begin{array}{l} \mathsf{Conjecture} \\ \forall _X \Big( \mathit{IsSorted}[\mathit{Sort}[X]] \land \mathcal{M}[X] = \mathcal{M}[\mathit{Sort}[X]] \Big) \end{array}$

- The conjecture is split in two;
- The proofs in *Theorema* are automatically generated by our prover which uses:
  - some special inference rules;
  - definitions and additional lemmas in the knowledge base.

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## Implementation Overview

**The prover: a collection of rewrite rules** corresponding to inferences.

- A proof situation (assumptions, goal)  $\stackrel{\mathrm{rule}}{\longrightarrow}$  new proof situation
- Alternatives: an AND-OR proof tree is created,
- Some of the alternatives may fail the *termination* is ensured by the *Theorema* mechanism for controlling the depth of the proof tree.

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## Implementation Overview

The **Theorema**-based prover uses the the methods:

- *Classical* propositional and first order inferences similar to the ones from sequent calculus.
- Generalized Noetherian induction that finds inductive hypotheses automatically.
- *Domain specific* methods for the types handled by the prover (multisets, lists).

These methods are implemented as:

- *Inference rules*: describe how to change the proof status in one proof step.
- Strategies: describe how to combine several inference rules.

# R1. Generalized induction

- Uses the Noetherian induction based on the well-founded ordering between lists;
- Checked syntactically by a meta-relation between terms induced by the strict inclusion of the multisets of the terms (U < V is determined by M[U] ⊂ M[V]).</li>

When needed, this rule applies to introduce a novel induction hypothesis with a smaller list.

Example: the main goal is *IsSorted*[*Insert*[a<sub>0</sub>, b<sub>0</sub> ∨ U<sub>0</sub>]], then *IsSorted*[*Insert*[a<sub>0</sub>, U<sub>0</sub>]] is assumed, because U<sub>0</sub> is smaller than b<sub>0</sub> ∨ U<sub>0</sub>.

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# R2. Cascading

- When a goal cannot be proved, a new conjecture is generated from the current goal and by using only the assumptions that are needed (the ones which contain the Skolem constants occurring in the goal);
- The conjecture is of the form  $\underset{X,Y}{\forall} A[X,Y] \implies G[X,Y]$

where

- X, Y are the Skolem contants from the current goal,
- A is composed from the needed assumptions, and
- G is the current goal;
- A new proof attempt starts, and typically, the novel generated conjecture corresponds to the verification of auxiliary functions used in the sorting algorithms.

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# R3. Preserving multisets

This rule is based on the following principle: the formula

$$E_1[x_1, x_2, ..., X_1, X_2, ...] \le E_2[y_1, y_2, ..., Y_1, Y_2, ...]$$

where only  $\smile$ , *Insert*, and *Merge* occur in the expressions  $E_1$  and  $E_2$ , can be transformed into:

$$x_1 \leq y_1, y_2, \ldots Y_1, Y_2, \ldots \wedge x_2 \leq y_1, y_2, \ldots Y_1, Y_2, \ldots \wedge \ldots$$

$$\wedge X_1 \leq y_1, y_2, \ldots Y_1, Y_2, \ldots \wedge X_2 \leq y_1, y_2, \ldots Y_1, Y_2, \ldots \wedge \ldots$$

(Each argument of  $E_1$  is smaller than each argument of  $E_2$ .) **Example:** A goal (or an assumption) of the form

$$Insert[a, T] \leq Merge[U, b \lor V]$$

is transformed into

$$a \leq U \land a \leq b \land a \leq V \land T \leq U \land T \leq b \land T \leq V.$$

## The algorithms

- Insert–Sort
- Merge–Sort
- Bubble–Sort
- Quick–Sort
- Patience–Sort
- Min–Sort
- Max–Sort
- Min–Max–Sort

Example: *Min–Max–Sort* returns the sorted version of the input list. It places the minimum of the input list at the beginning of the output and the maximum at the end of the it, and then applies recursively to the list of the remaining elements, selected by the function *TrimMM*.

## Algorithm

$$\begin{pmatrix} \forall (TrimMM[a \smile (b \smile U)] = TrimMmA[a, b, U]) \\ a \leq b \\ \forall (TrimMM[a \smile (b \smile U)] = TrimMmA[b, a, U]) \\ b \leq a \end{pmatrix}$$

### Algorithm

$$\begin{pmatrix} \forall (TrimMmA[a, b, \langle \rangle] = \langle \rangle) \\ a,b,c,U \\ c < a \\ \forall (TrimMmA[a, b, c \smile U] = a \smile TrimMmA[c, b, U]) \\ c < a \\ \forall (TrimMmA[a, b, c \smile U] = c \smile TrimMmA[a, b, U]) \\ (a \le c \land c \le b) \\ \forall (TrimMmA[a, b, c \smile U] = b \smile TrimMmA[a, c, U]) \\ b < c \end{pmatrix}$$

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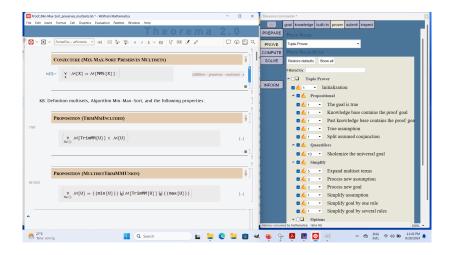
# Computation with the Algorithms

4.4.00	;orithm (MinMaxSort)	Theorema 2.0
ALG	ORTHM (WINNAXSORT)	×
In[83]:=	$\langle MMS[\langle \rangle] = \langle \rangle \rangle$	(Min – Max – Sort – I) 🗙
In[84]:=	$ \begin{pmatrix} \forall   MHS[\mathbf{a} \sim \langle \rangle] = \mathbf{a} \sim \langle \rangle \end{pmatrix} $	(Min – Max – Sort – 2) 🗙
In[85]:=	$\left[ \begin{array}{c} \forall \\ a_{a,b,U} \end{array} \right  \text{MMS} \left[ a \sim \left( b - U \right) \right] = \text{min} \left[ a \sim \left( b - U \right) \right] \sim \left( \text{MMS} \left[ \text{TrimMM} \left[ a \sim \left( b - U \right) \right] \right] \sim \text{max} \left[ a \sim \left( b - U \right) \right] \right) \right) \right]$	(Min – Max – Sort – 3) X
Compute           In[90]:=         MMS           Out[90]=         3 -	\$[3 ~ (\)] ()	
	<b>5</b> [3 ~ (2 ~ (3 ~ (6 ~ (8 ~ (10 ~ (\)))))] (3 ~ (3 − (6 − (8 − (10 − (\))))))	
	$ \begin{bmatrix} 10 & (2 - (3 - (6 - (8 - (10 - ())))) \end{bmatrix} \\ (3 - (6 - (8 - (10 - (10 - ())))) ) $	
	5[1 - (2 - (3 - (6 - (8 - (10 - ⟨⟩))))] (2 - (3 - (6 - (8 - (10 - ⟨⟩)))))	
	\$[10~(4~(3~(2~(8~(1~()))))] (2~(3~(4~(8~(1~())))))	

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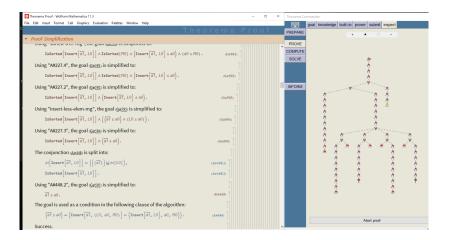
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# Proving in Theorema



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## Generated Proof and Proof Tree in Theorema



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#### Results

• A Theorema prover for proof-based algorithm synthesis and verification on lists using multisets.

### This case study

- shows that, even though the algorithms are very well-known, proving the correctness is not trivial;
- the use of multisets is very important as it allows to express more easily the fact that two lists have the same elements;
- the techniques used lead to more efficient proofs, and simplify the proving process → in *Theorema* the proofs are generated in a few seconds and are easy to understand.

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*Theorema* is a very nice automated theorem prover that can be used for both

- Teaching:
  - Automated Theorem Proving,
  - Algorithm Synthesis and Mathematical Theory Exploration.
- Research: algorithm synthesis and verification.

### Ongoing and future work $^1$

- Verify robotic algorithms in *Theorema* (e.g. Dijkstra, A\*, ...)
- Increase the automation of proving and of finding necessary lemmata in *Theorema*

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#### Thank you for your attention!

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